

# AOS closed loop with imSim







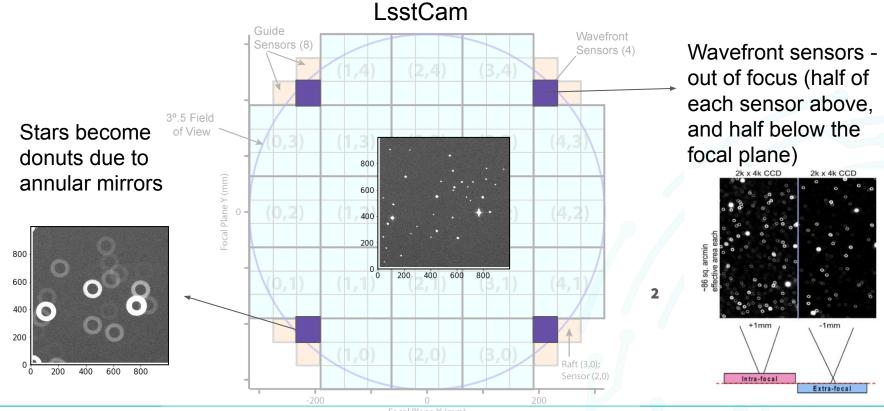








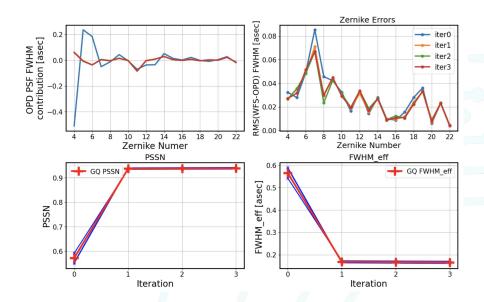
#### **Active Optics System: wavefront sensors**





#### **AOS Closed Loop**

- The Active Optics System (AOS) team uses closed loop simulations to test the performance of the AOS algorithms in a variety of situations.
- In the closed loop we start with the telescope's optics in a perturbed state and iterate solving for the wavefront error and calculating corrections to the optical system until we reach convergence of the algorithm.

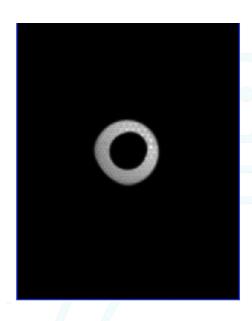




### AOS Closed Loop Code (ts\_imsim)

- Closed Loop implementation with imSim
  - Configure imSim
    - Set up perturbations in initial telescope configuration file.
    - Set other imSim configurations in smaller configuration files specific to each submodule (telescope perturbations, atmospheric PSF, sky model, vignetting...).
    - Define a pointer file that has the configuration files you want to use.
  - Take imSim configuration and run simulation of first iteration
  - Analyzes image quality with the OPD
  - Ingests imSim donut images into butler repository





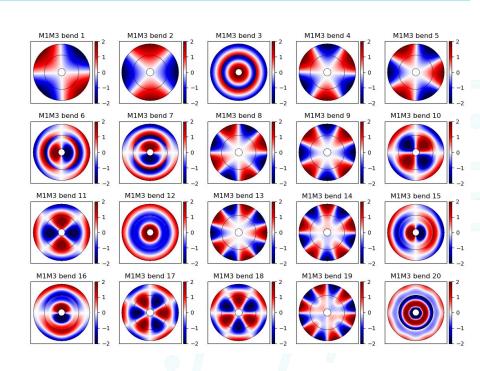
Left: OPD, Right: Simulated Wavefront Sensor



## AOS Closed Loop Code (ts\_imsim)

#### Closed Loop implementation with imSim

- Runs ingested images through the AOS Wavefront Estimation Pipeline (WEP)
- WEP produces estimates of the wavefront error on each sensor in terms of Zernike polynomials
- Optical Feedback Control (OFC) calculates corrections to hexapods and mirrors
- Degree of freedom corrections are added into imSim configuration for next iteration
- The 50 DOFs are:
  - 0-4: M2 dz, dx, dy, rx, ry
  - 5-9: Cam dz, dx, dy, rx, ry
  - 10-29: M1M3 20 bending modes
  - 30-49: M2 20 bending modes



Credit: Josh Meyers

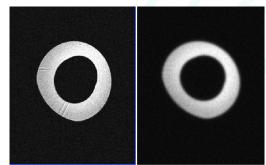


#### Why move to imSim?

#### Phosim Issues

- Camera rotation not implemented
- Shape of donuts on wavefront sensors don't match model donuts from Zemax
- Unable to make changes to Phosim code to fix problems
- Required maintaining a separate package to process output into butler ready images
- Speed



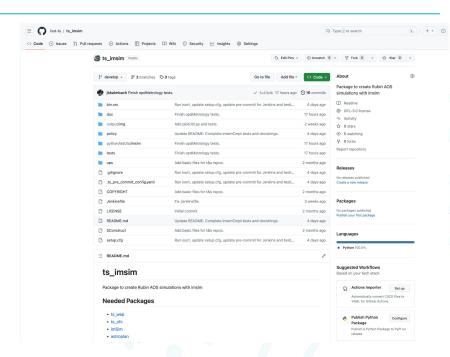


Donuts generated in closed loop. Left: Phosim Right: imSim



#### **Current ts\_imsim status**

- Closed loop running on LSSTCam corner wavefront sensors
- Still need to implement LSST Full Array Mode (LSST FAM)
- Convergence of closed loop under investigation (more in a minute)
- Integrated with T&S Jenkins CI
- Hosted on github: https://github.com/lsst-ts/ts imsim

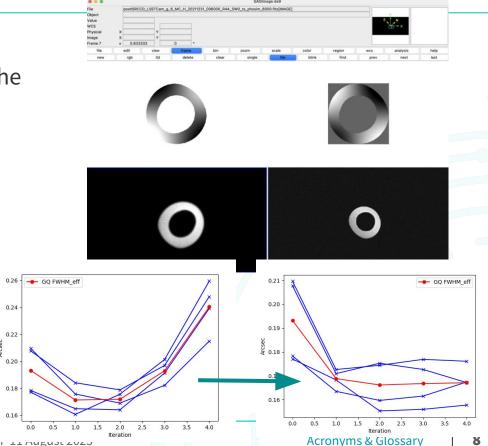




#### **Closed Loop Convergence with imSim**

0.24

- Using the same process as we used with phosim we were unable to get the closed loop to converge in initial testing
- Discovered that on some bending modes there seems to be a sign flip between phosim and imSim
- Flipping the signs of certain Zernike coefficients to offset this seems to correct this and the closed loop converges





#### **Future Development**

- Validate performance with camera rotation
- Add additional camera settings (LSST FAM)
- Move to use the SkyCatalog interface for generating input
- Tie in to use OpSim so we can simulate sequences of observations with realistic observing conditions
- Keep synchronized with new imSim features that increase realism