

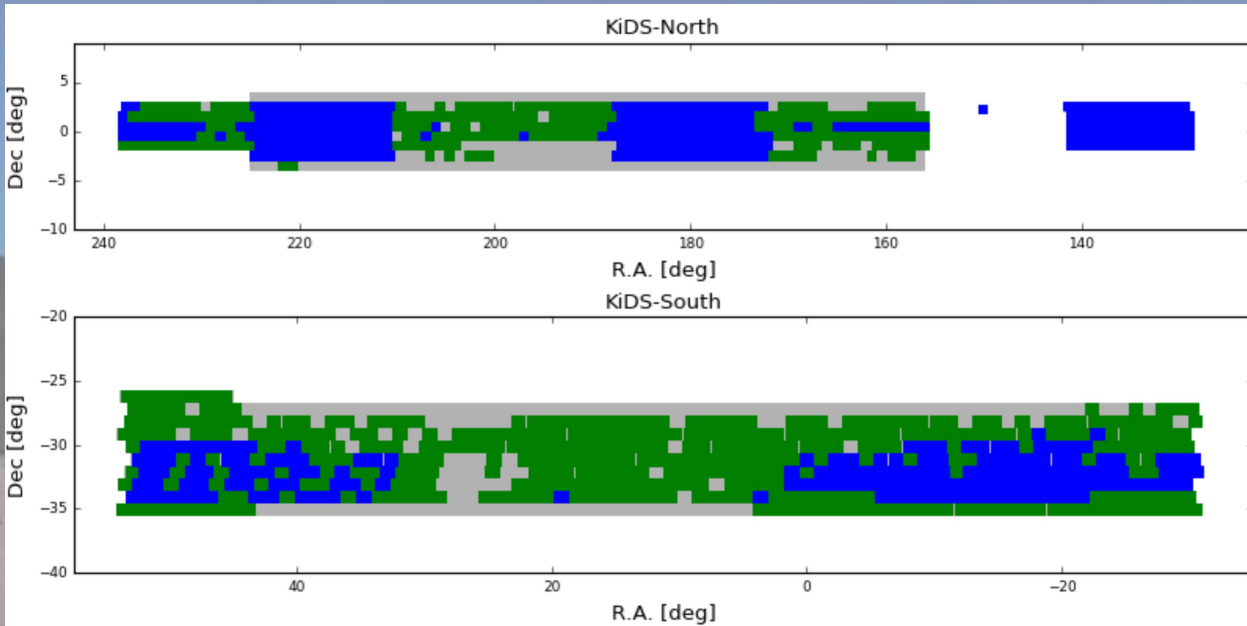


Galaxy Photometry

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- This is not a complete review of (the state of the art of) galaxy photometry
- Most will be about how we approach this problem in the Kilo-Degree Survey (KiDS + VIKING)
(Kuijken et al. 2019, A&A 625, A2; Wright et al. 2019, A&A 632, A34)
- **Statement of the problem**
 - **possible approaches**
 - **GAaP in KiDS**
 - **thoughts on way forward**
- Not addressed: overlapping sources
- Not much on photometric calibration

The Kilo-Degree Survey: basic stats



DR3 15M. DR4 33M.



Final area **1350 deg²**

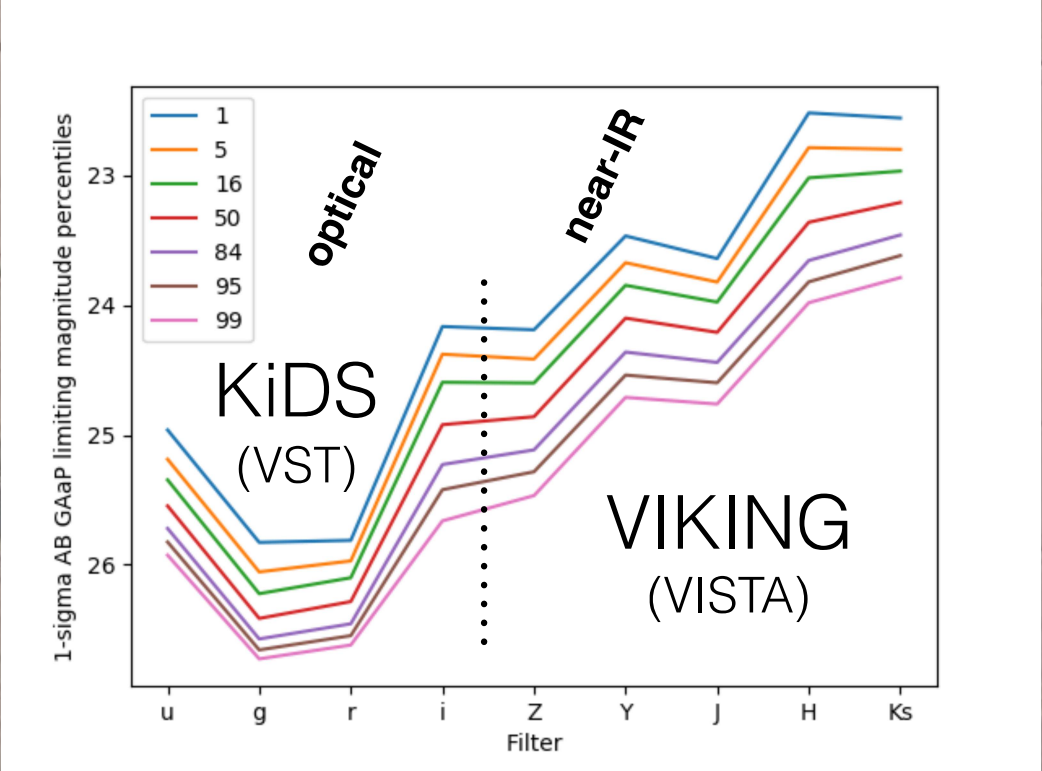
Lensing images (r):

Seeing **0.7''**

Depth **25^m** (5 σ AB)

PSF Ellipticity **0.03**

Colours:
ugriZYJK_s

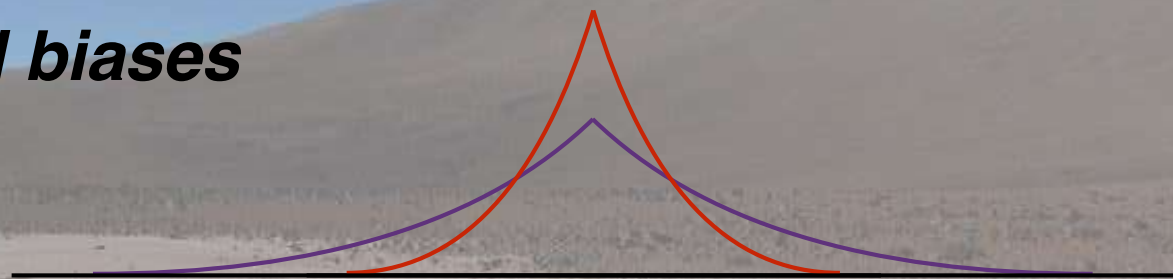


What do we mean by galaxy photometry

- **Total magnitudes**, in various bands
→ stellar luminosities, masses, baryon budget, etc
- **Colours**
→ photometric redshifts, stellar populations, ...
- These are different requirements!
- They only coincide for unresolved (point) sources
- I am not talking about surface brightness photometry here

1. Total magnitudes

- Galaxies have no sharp edges
- Need a model to fit wings as they disappear below the noise
 → **model biases**



- e.g. in 1D: fit flux=1 $\frac{e^{-|x|/a}}{2a}$ 'galaxy' with $F \times \frac{e^{-|x|/b}}{2b}$ model
- assume uniform noise: lsq. fit gives $F = \frac{\sum MD}{\sum MM} = \frac{2b}{a+b}$
 - model too wide ($b > a$): F overestimated (due to under-constrained wings). Up to factor 2!
 - model too narrow ($b < a$): F underestimated up to arbitrary factor!

1. Total magnitudes

- *These biases change with PSF!*

- e.g. in 1D: fit $\frac{e^{-x^2/2a^2}}{\sqrt{2\pi}a}$ 'galaxy' with $F \times \frac{e^{-x^2/2b^2}}{\sqrt{2\pi}b}$ model.

- for uniform noise, lsq. fit gives $F = \frac{\sum MD}{\sum MM} = \sqrt{\frac{2b^2}{a^2 + b^2}}$

- now assume Gaussian seeing p . This changes the galaxy and model sizes (add p in quadrature)

- now best-fit fit $F = \frac{\sum MD}{\sum MM} = \sqrt{\frac{2b^2 + 2p^2}{a^2 + b^2 + 2p^2}}$

- These model biases change with PSF (and get smaller as PSF gets worse)

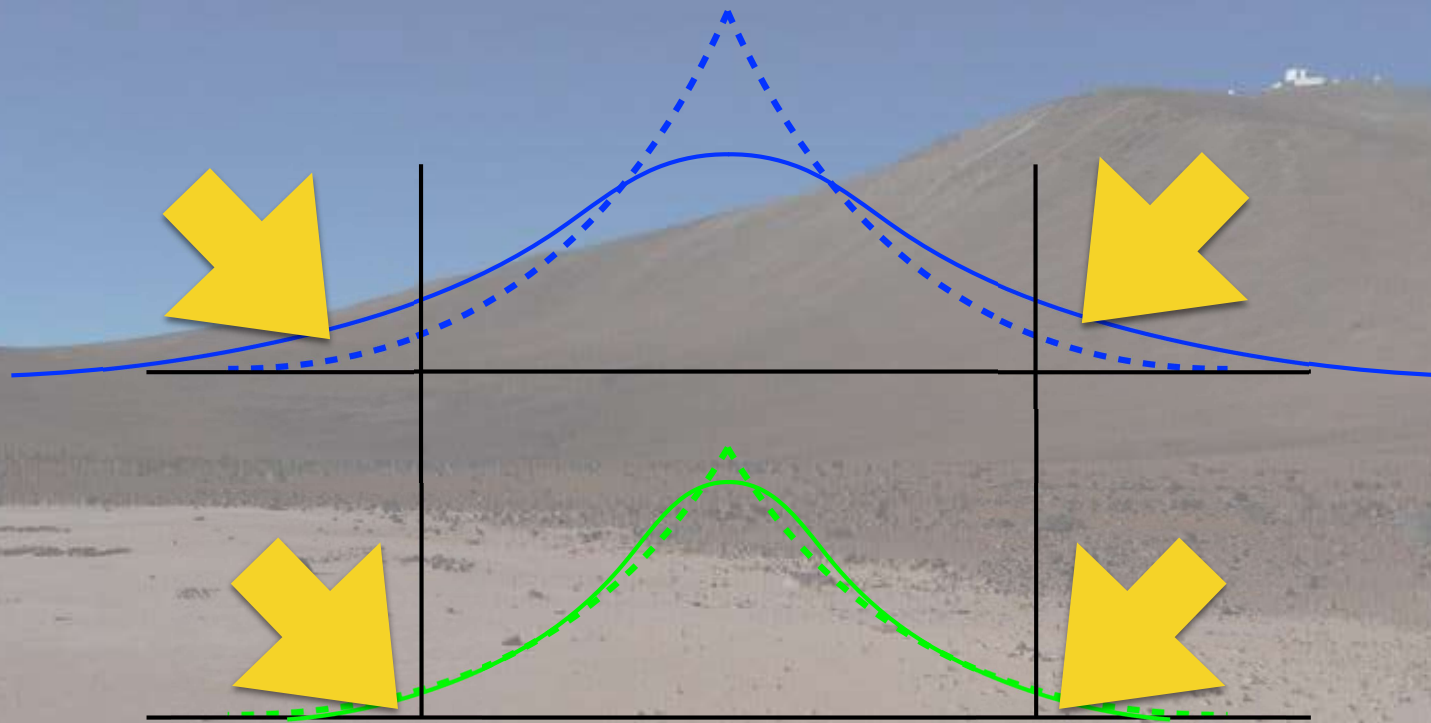
1. Total magnitudes are hard/impossible

- Total magnitudes are model-dependent
- Total magnitudes are observation-dependent
- Total magnitudes are ill-defined in practice (without mentioning sky subtraction!)
- Hence the wide variety of proxies:
 - Petrosian
 - aperture + corrections
 - isophotal + extrapolation (fitted isophote or segmentation*)
 - Sersić, disk+bulge,...
 - ... all of which need to take account of the PSF to interpret them
- Fred Moolekamp's talk Tuesday discussed much of this
- *Also see ProFound/ProFit (Robotham et al., [arXiv:1802.00937](https://arxiv.org/abs/1802.00937))

2. Colours

- Ideally, colour \leftarrow flux ratio between two total magnitudes
- ... but, see before.
- Why do we need colours of galaxies?
 - stellar populations, dust, ...
 - photometric redshifts
- Typically you can get away with only using the bright parts of a source for this
 - avoid the extrapolation errors of model magnitudes
 - use higher SNR parts of the source
- So high-fidelity colours can be measured from apertures
 - ... provided PSF differences are accounted for

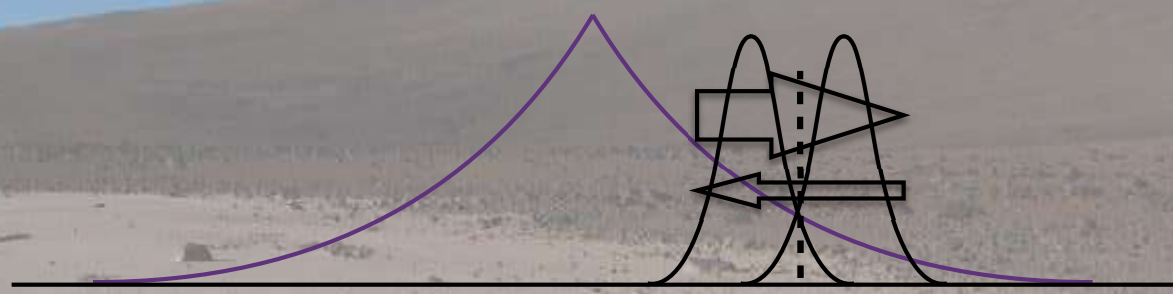
2. Colours



- fraction of flux missed is different:
 - ⇒ same aperture on different-seeing data is meaningless unless aperture includes all the flux
- BAD. You need to allow for seeing differences

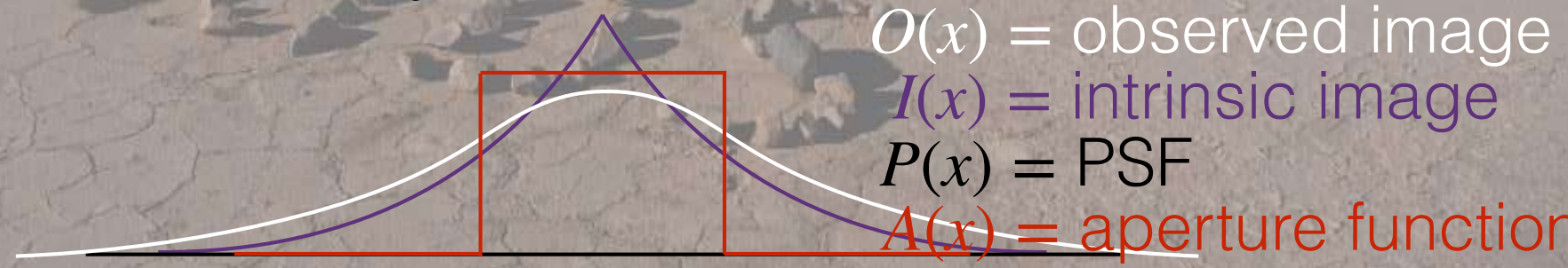
Colours and apertures

- The PSF scatters photons in the source
- Unequal fractions scatter into, and out of, any aperture



- Fraction depends on galaxy surface brightness profile, and on seeing, and on aperture
- What do you actually measure with aperture photometry?

$$F_{Ap} = \int O(x)A(x)dx = \int (I \otimes P)(x)A(x)dx$$



$O(x)$ = observed image
 $I(x)$ = intrinsic image
 $P(x)$ = PSF
 $A(x)$ = aperture function

$$F_{Ap} = \int O(x)A(x)dx = \int (I \otimes P) \times A dx$$

- Swap the convolution and the product:

$$F_{Ap} = \int O(x)A(x)dx = \int I \times (P \otimes A) dx$$

- so F_{Ap} = ap.phot. on *Intrinsic* $I(x)$, with aperture $A \otimes P$
 - as long as this convolved aperture is the same, you are comparing apples to apples and can measure useful colours
- Various approaches:
 1. when comparing 2 images, convolve each image with the other's PSF and use matched apertures
 2. degrade seeing of best image to worst
 - approximately or carefully (see DIP talks yesterday)
 3. standardise PSF and aperture and control aperture on *intrinsic* image $A \otimes P$.

- Particularly for many-band surveys a standard(ised) PSF and aperture is most flexible
- GAaP: **Gaussian Aperture and PSF**
 - standardise PSF to Gaussian
 - use (elliptical) Gaussian apertures
 - chosen to optimise SNR i.e. \sim size of intrinsic image \otimes typical PSF
 - Benefits
 - Easy to add more bands when then come in
 - \sim Optimal SNR for colours
 - Central parts of galaxies are more photo-z friendly
 - Combine data from different cameras, pixel grids, etc.
 - But
 - formalism breaks down for very large ($>x2-3$) seeing ratios
 - No attempt to get total fluxes!

- Recall

$$F_{Ap} = \int I \times (P \otimes A) dx$$

- Assume P and A are Gaussians: then so is $P \otimes A$.
- Convolutions and deconvolution are easy

- For each source, pick a pre-seeing ap.fn. $W = e^{-\frac{1}{2}m^2/w^2}$ (adapt size/shape for best SNR). *same one for all bands!*

elliptical radius

- For each band, compute post-seeing ap.fn. $A = W \otimes^{-1} P$ and measure the aperture flux $F_W = \int O(x)A(x) dx$

- These fluxes all correspond to the same pre-seeing aperture function on the galaxy. ✓ ✓ ✓
- Can do this for a range of aperture sizes and so measure curves of growth, gradients, etc. (also annuli)
- Error estimate is easy if covariance matrix of O is known

But...

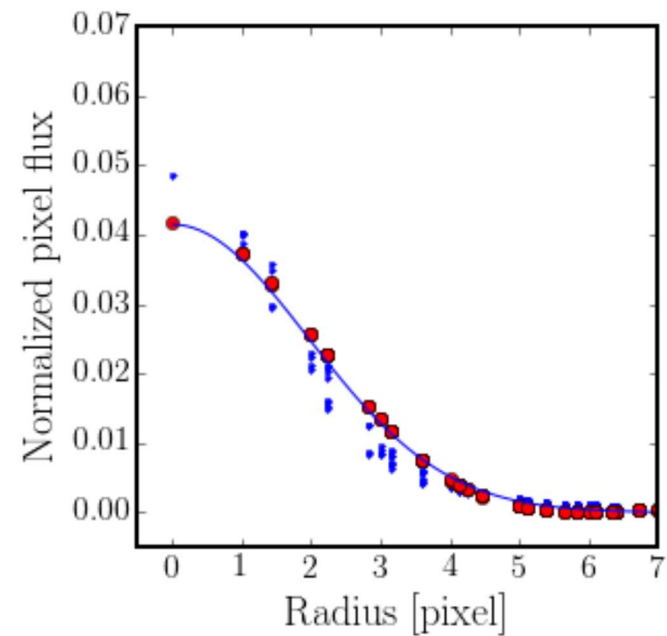
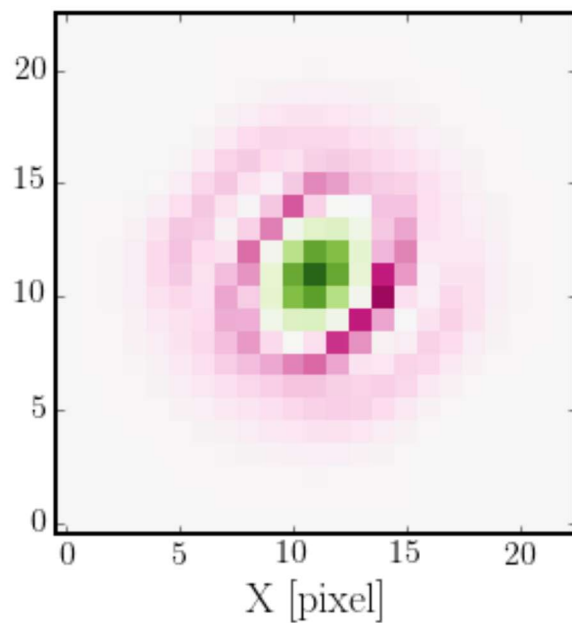
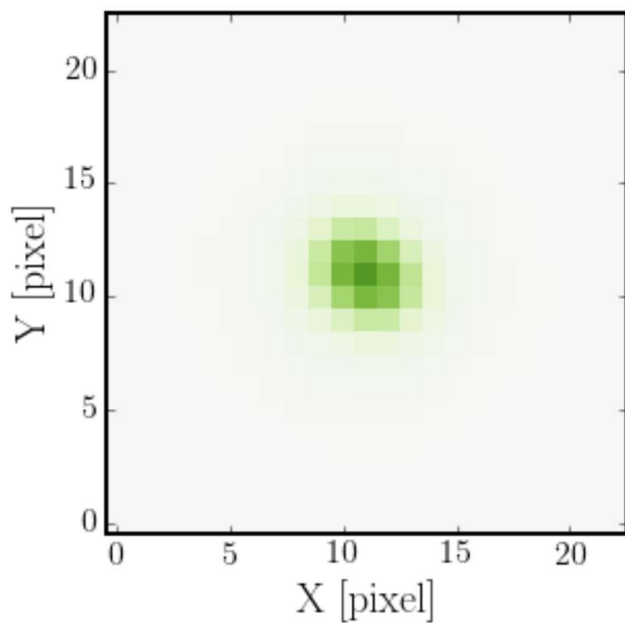
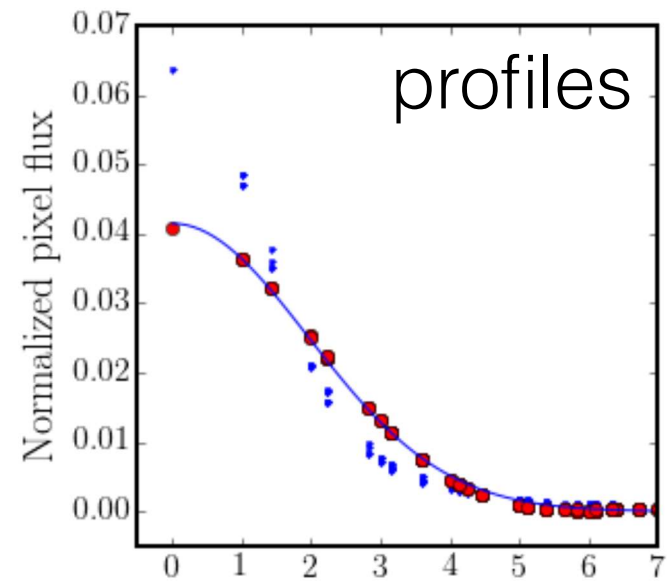
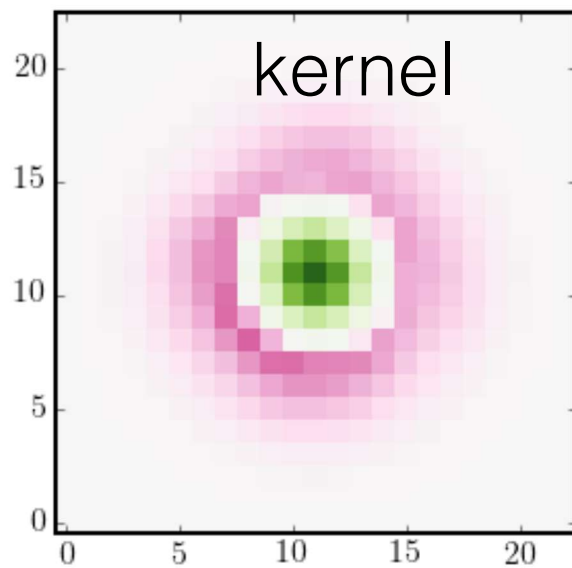
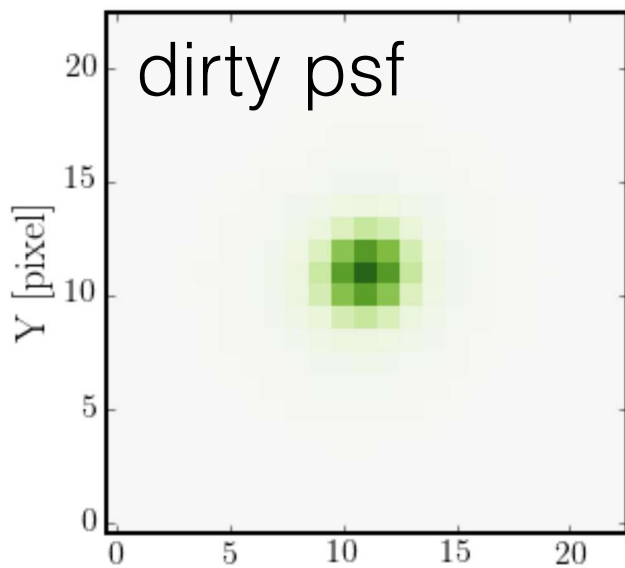
- The PSF is not Gaussian
- Make it so

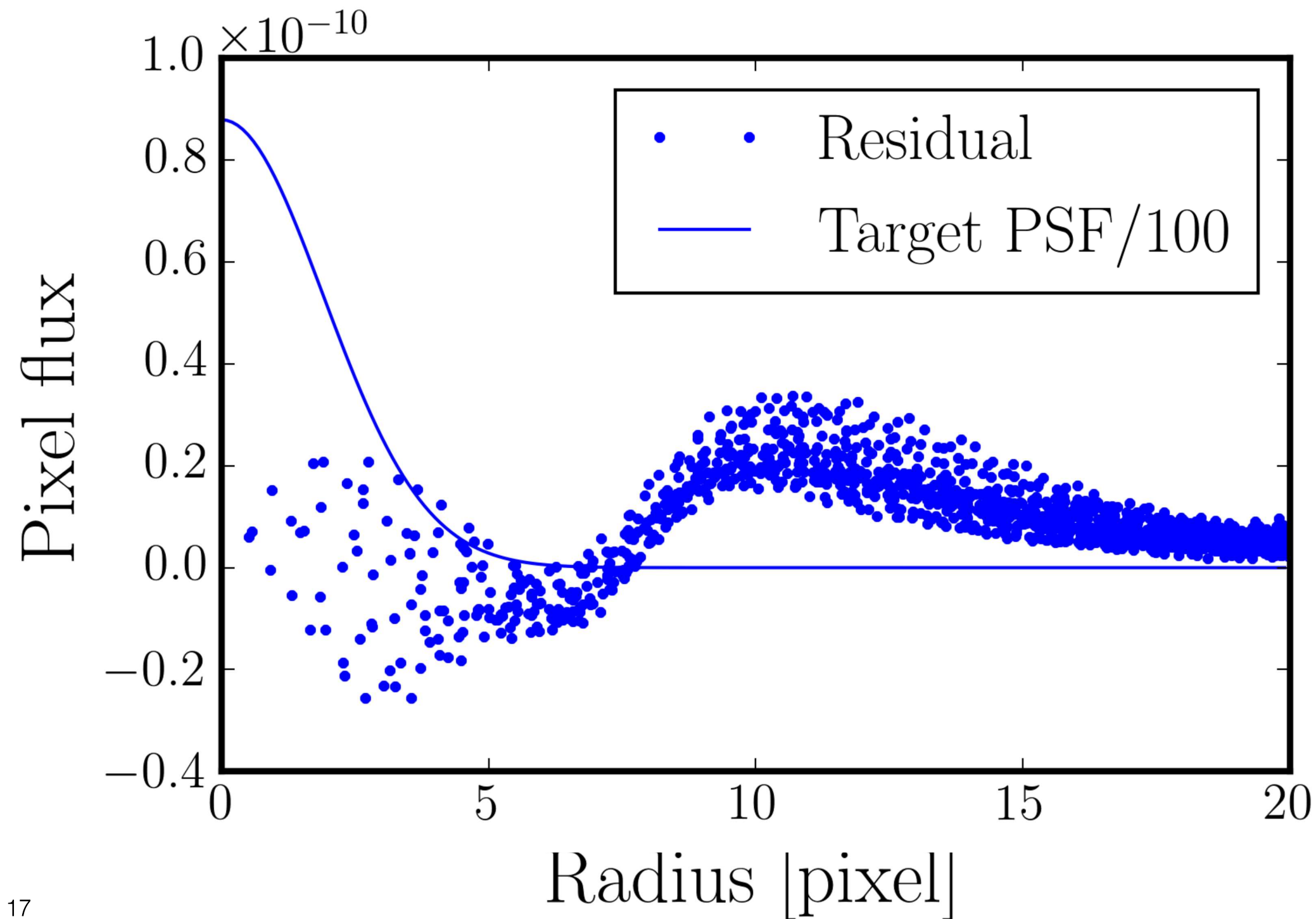


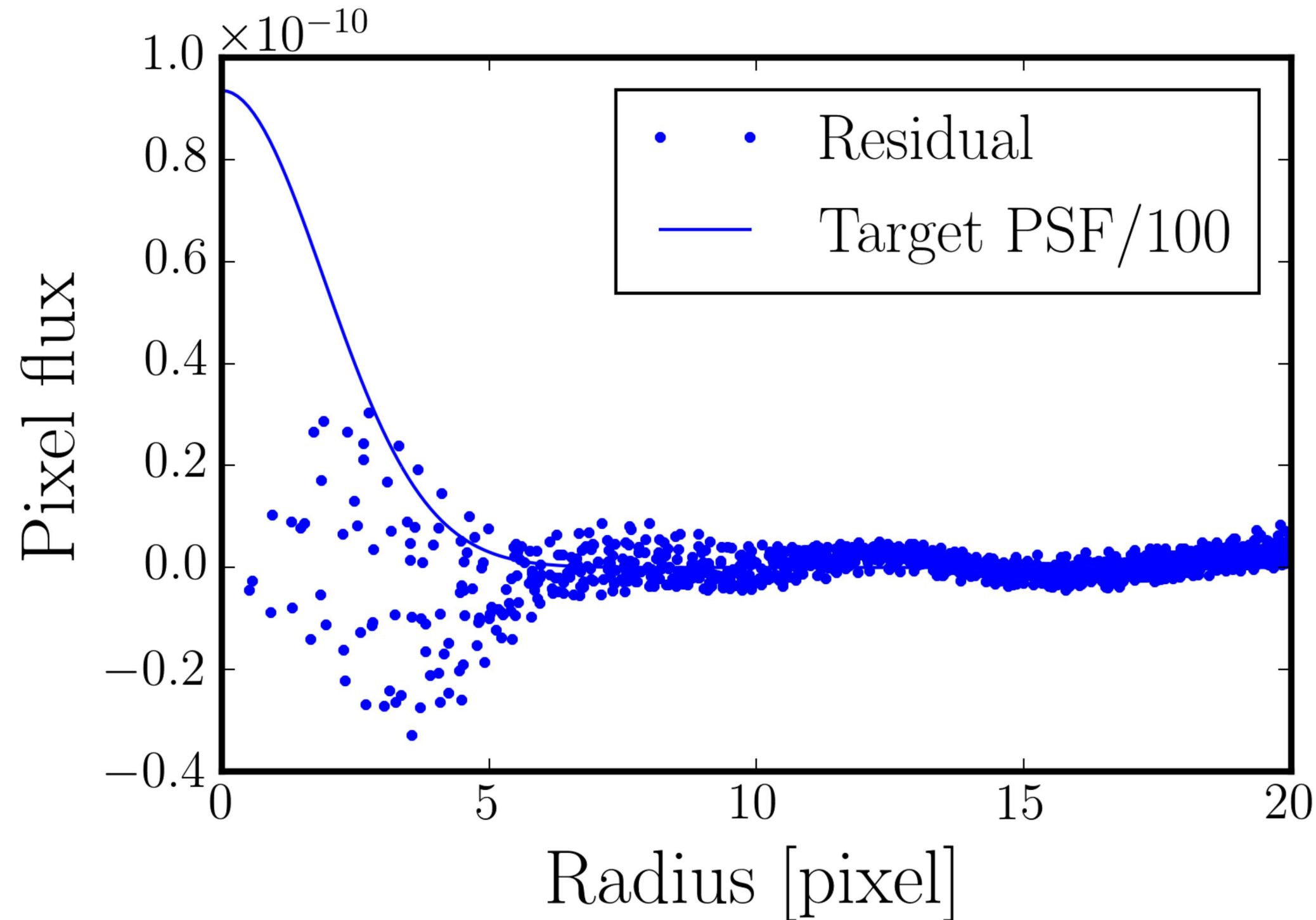
- *This is a key step*
- Current implementation
 - find all (~ 1000) stars, deduce seeing, set target PSF size
 - set target Gaussian PSF core $\sim 1.2x$ wider than original
 - star by star, find optimal Gaussianization kernel
 - use overconstrained double shapelet model

$$\sum_{i,j=0}^{i+j \leq 8} k_{ij} H_i(x/\beta) H_j(y/\beta) e^{-r^2/2\beta^2} + \sum_{i+j \geq 3}^{i+j \leq 6} K_{ij} H_i(x/B) H_j(y/B) e^{-r^2/2B^2}$$

- fit smooth model to variation of the k_{ij}, K_{ij} coeffs. over the image
 - convolve the (co-added or not) pixels with variable kernel
 - **noise covariances** given by ACF of the kernel (easy in shapelet space)

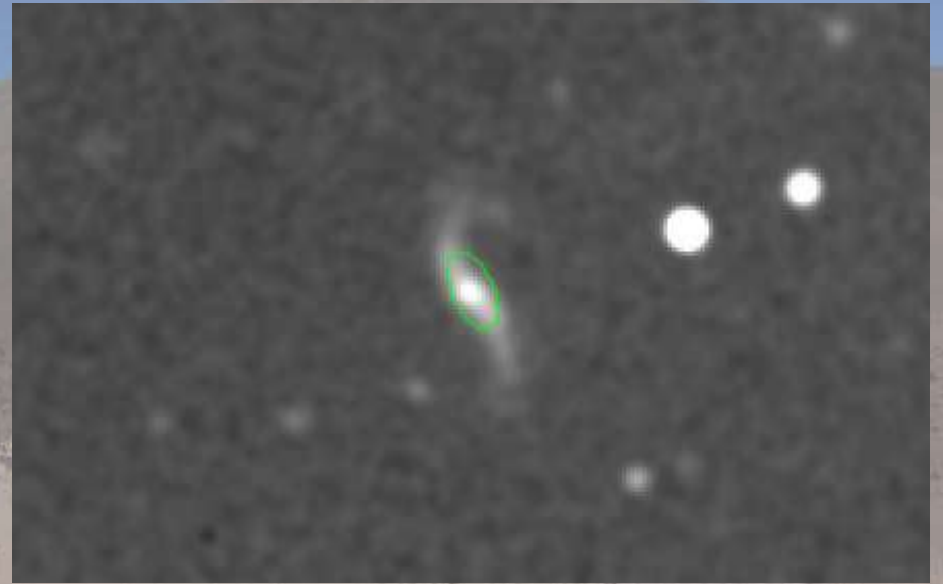




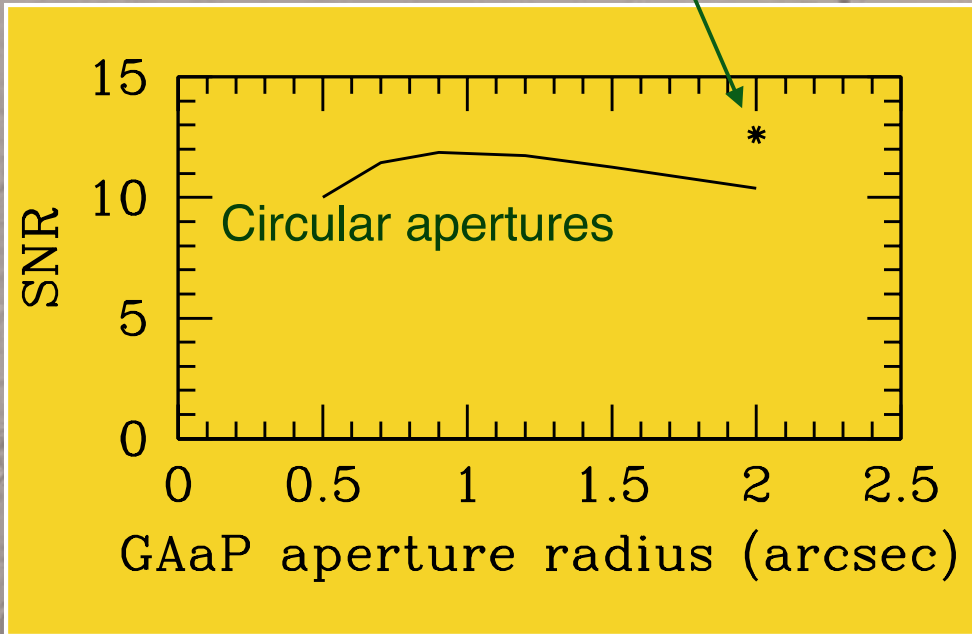


Example

- Broad SNR plateau
- gives some dynamic range for seeing differences between bands
- elliptical aperture helps SNR



Elliptical aperture

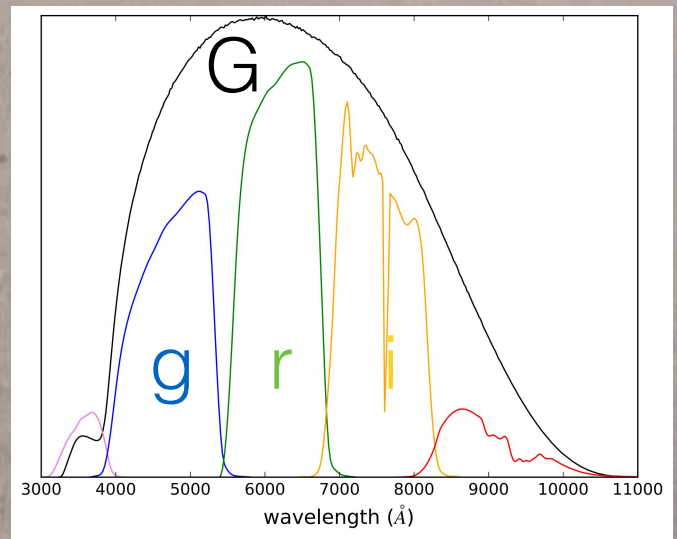
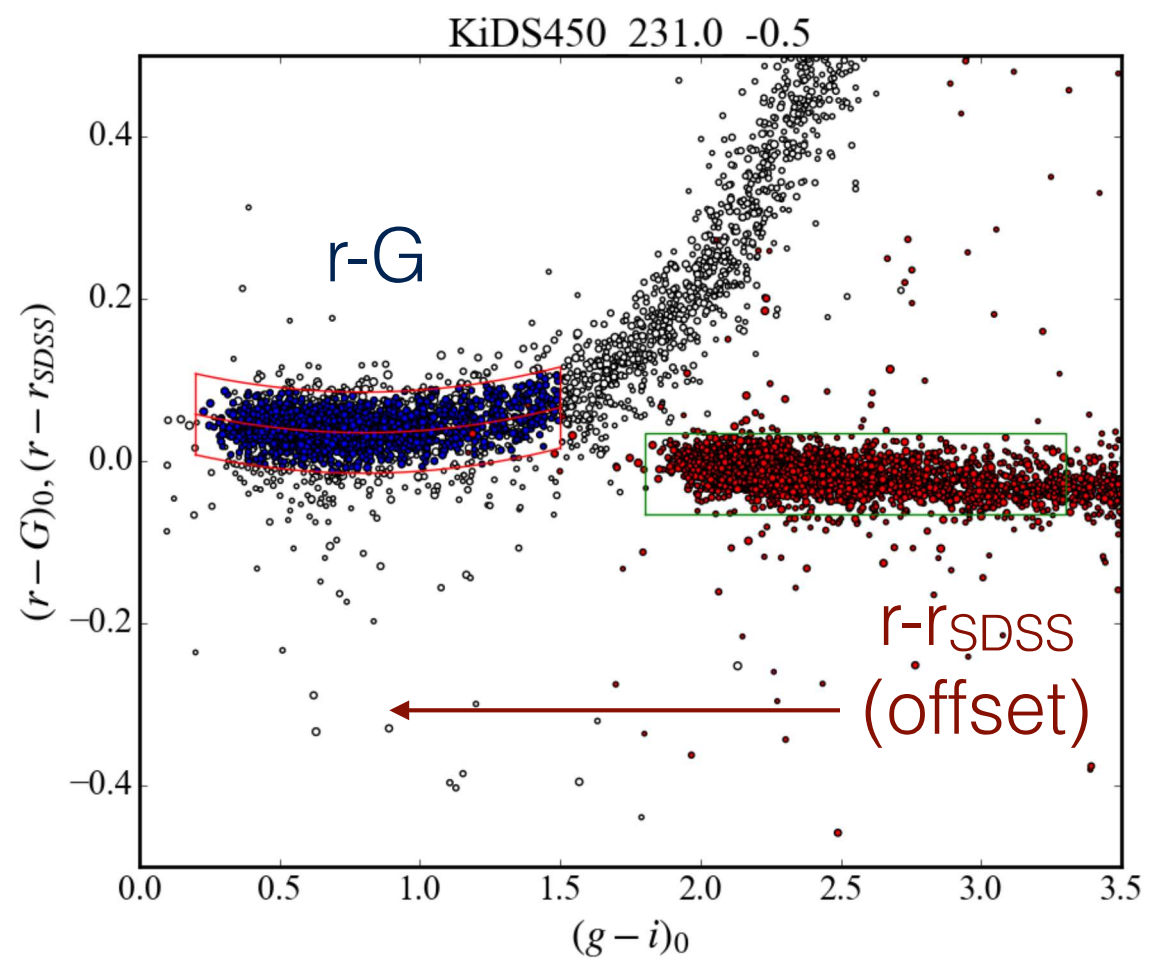


To emphasise

- We track noise covariance (see Jim Bosch's talk)
- Model it as a spatially variable shapelet expansion
- Allows analytic calculation for variance of any GAaP flux using only shapelet kernel and SExtractor weight image
- The result is only as good as your PSF Gaussianization
- Workflow in KiDS:
 - detect sources, determine aperture (on r-band co-adds)
 - PSF-Gaussianize ugri coadds, ZYJHK pawprints
 - (all with their own PSF width)
 - get GAaP fluxes for all bands, average multiple exp's
- Working on coadds only OK if PSF jumps are not a worry
- Use 2 apertures per source in case need to incorporate bad-seeing data in the SED

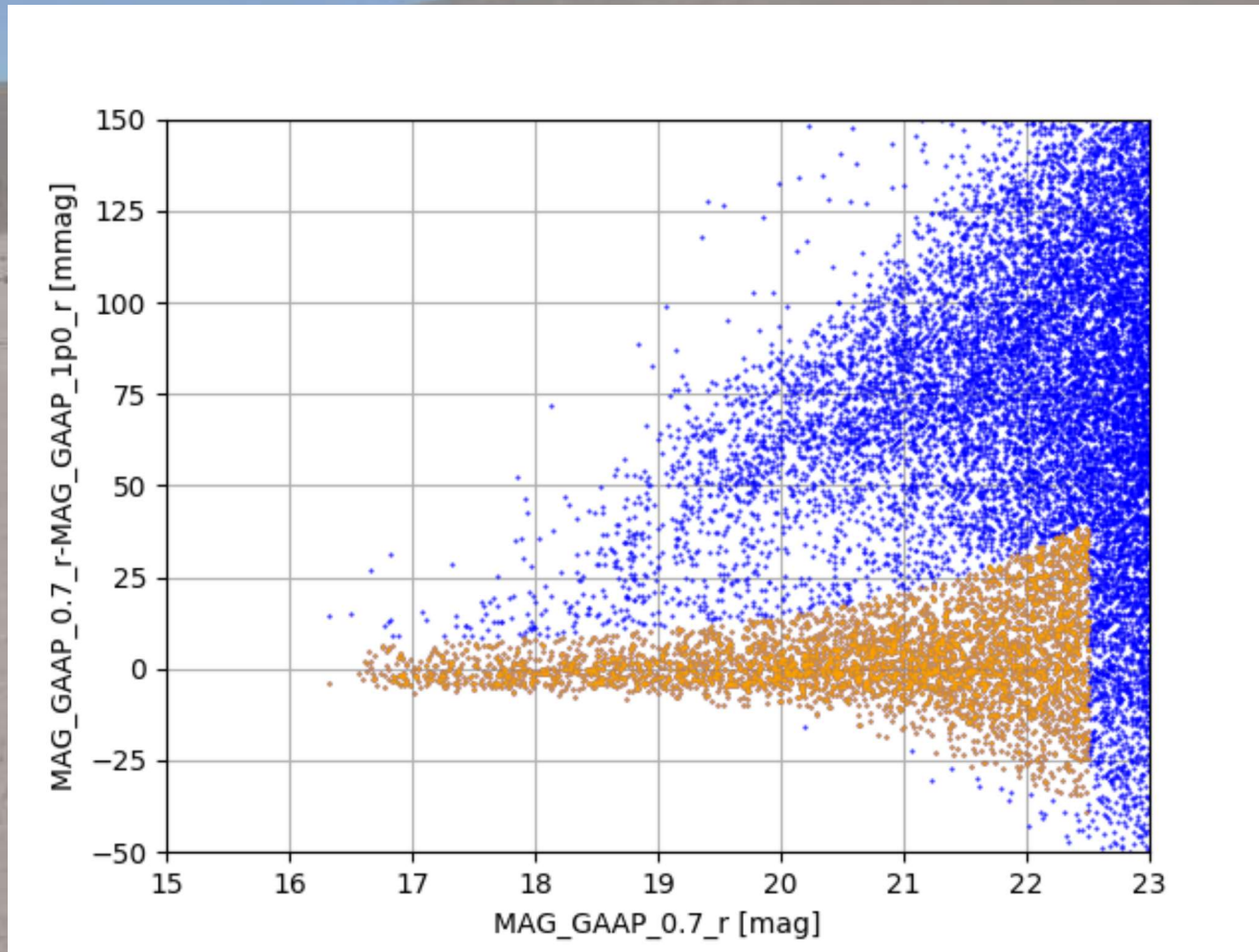
- For point sources GAaP flux = total flux
 - Follows from $W = e^{-\frac{1}{2}r^2/w^2}$: $\int F\delta(x)W dx = FW(0) = F$.
 - For a star any aperture should give the same GAaP flux
- This makes an integrated measurement of stars as photometric calibrators straightforward
- Nice star-galaxy separation tool

- photometric calibration from stars
- nightly zeropoint from standard star fields
- overlap between tiles
- stellar locus fit ($g-r$, $r-i$)
- r tied to **Gaia** G
- Will improve further with Gaia DR2 (multi-colour)



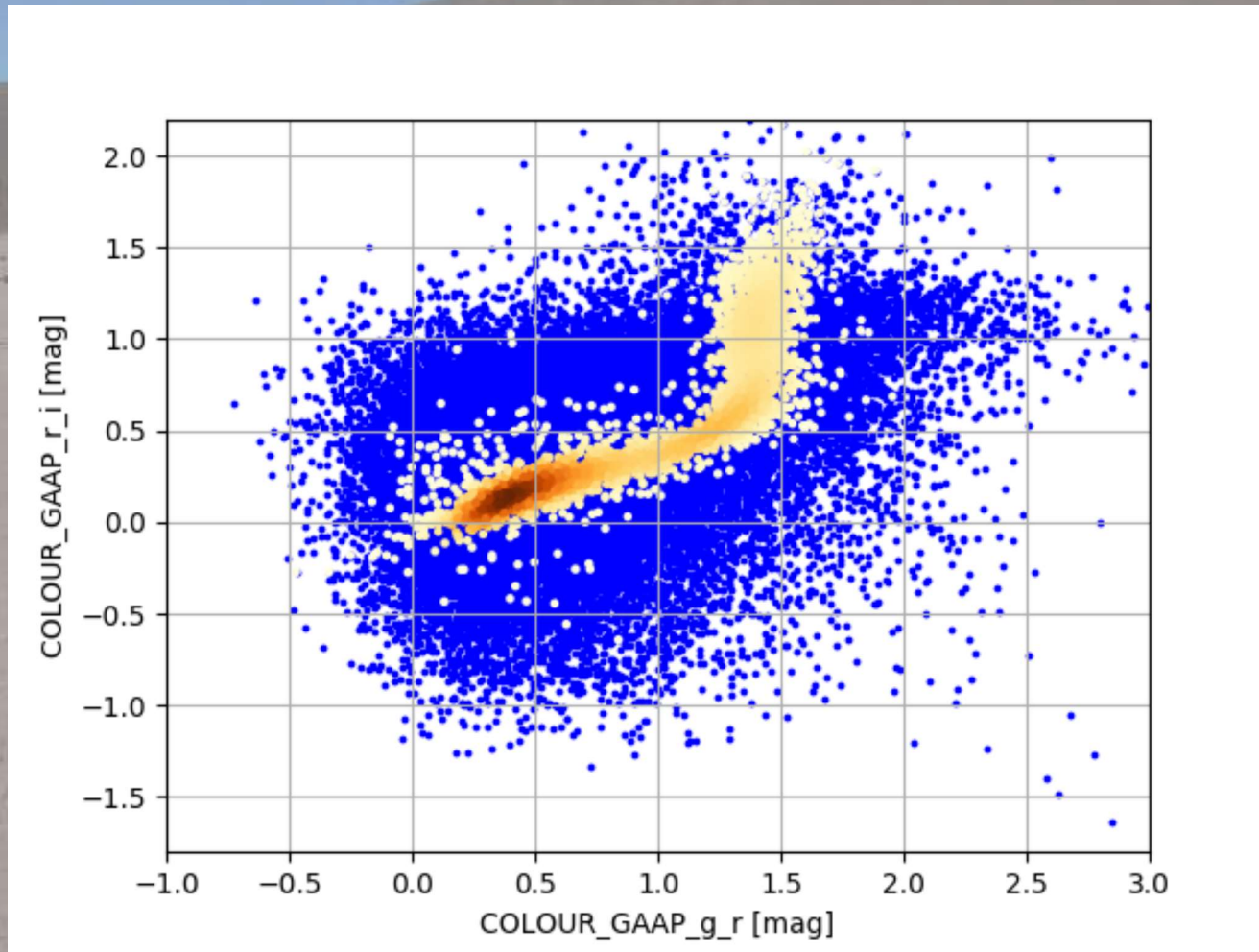
Star-galaxy separation

- GAaP curve of 'growth': compare $\sigma=0.7''$ and $1.0''$ apertures



Star-galaxy separation

- GAaP curve of ‘growth’: compare $\sigma=0.7''$ and $1.0''$ apertures



- unresolved sources really are stars

Centroid & aperture bias



- Our aperture shape and centre is set by r band detection
 - noise bias (2nd order)
 - for point sources $\sqrt{2}\delta x \sim \text{FWHM}/\text{SNR}$
- Photometry error for point sources

$$\simeq W_{\text{pre}}(\delta x) \simeq e^{-1/\text{SNR}^2} \simeq 1 - 1/\text{SNR}^2$$
- Important for low-SNR detections

detection
SNR



- All KiDS photo-z are based on GAaP
- No issues combining 0.2" VST pixel data with 0.34" VISTA pixels
- Using data with seeing 0.45 — 1.3 arcsec
- Run time ~ minute per 300Mpix image
- Photo-z are calibrated by comparison to spectroscopic samples, imaged with same filters, instruments and depths as main sample
- So far it does the job

Possible further developments

- Skip the explicit generation of the Gaussianised-PSF image: instead
 - Calculate $(W \otimes^{-1} P) \times O$ directly for each source
 - Added advantage is greater simplicity of error estimate
 - Which route is more practical depends
 - on how many apertures you want to photometer
 - whether you have other uses for the Gpsf image
 - e.g. shape measurement (SNAP-G, Herbonnet et al. 2017, A&A 599, A73)
- Alternative approach to PSF kernel modelling
 - Shapelet model is nice and stiff, but not necessarily the best